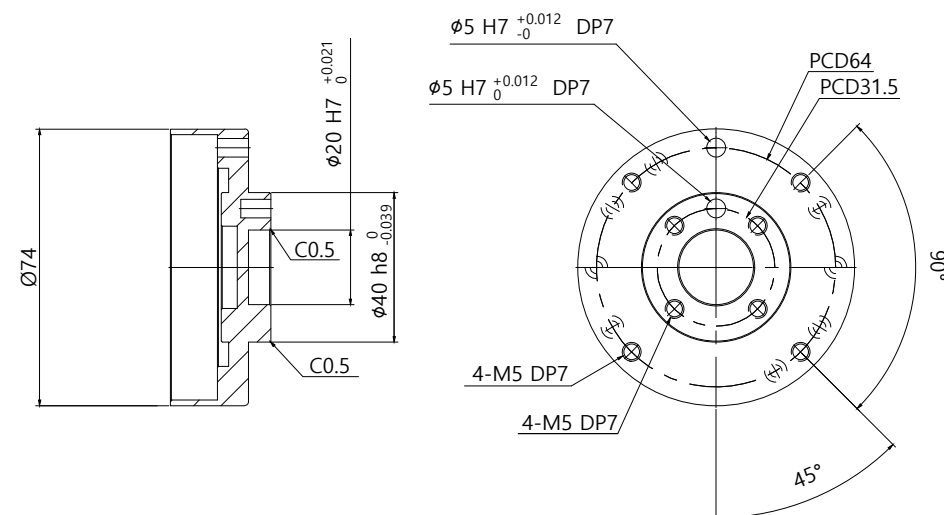
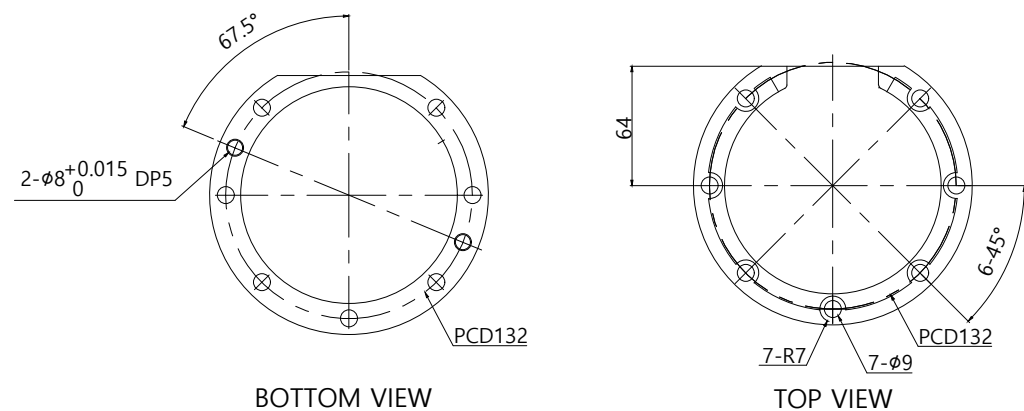


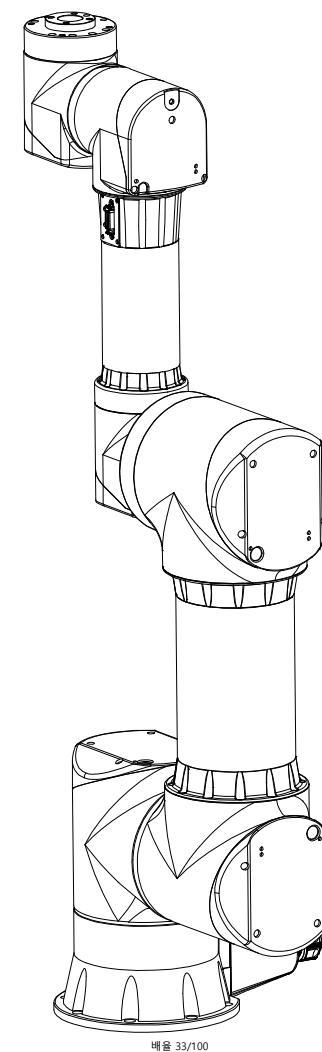
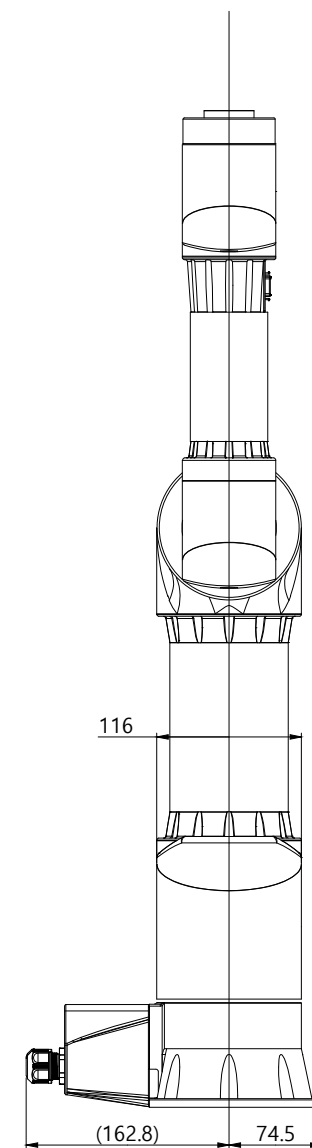
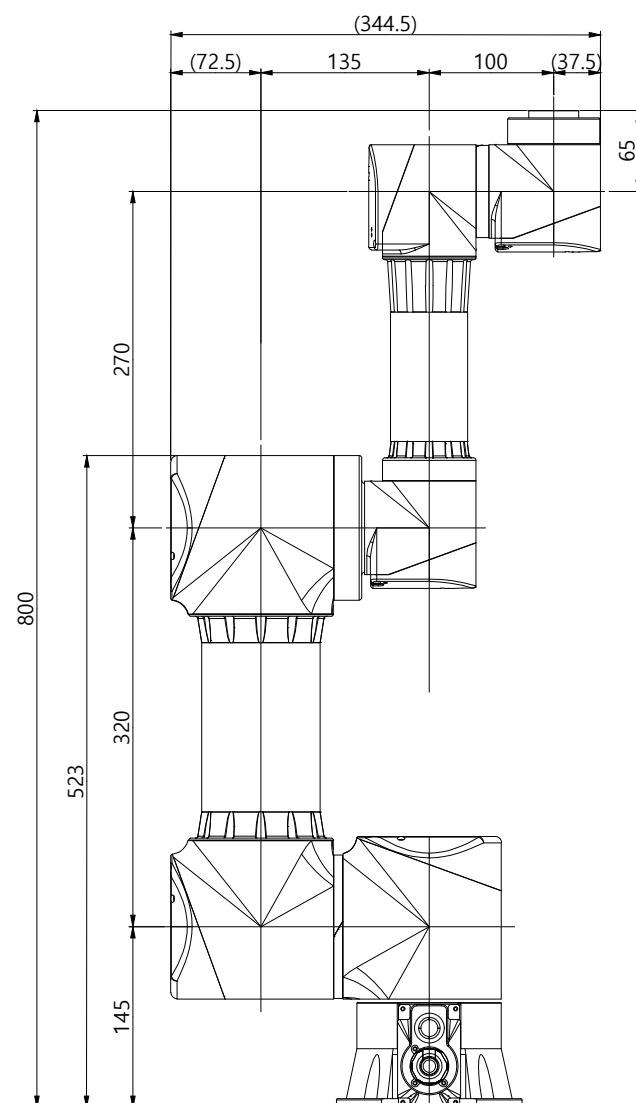
A

$$B$$
$$C$$
 $D$  $E$ 


## Top Flange



## Bottom Flange



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| RELEASE<br>OF<br>DRAWING | S<br>H<br>E<br>E<br>T |

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|------|------------|-------------|--------|------|--------|-------|----------|---|--|------|------------------------|------------------|-----------|-------------|
|      |            |             |        |      |        |       |          | REF: DRAWING  |  |      | PROJECT NO.            |                  | TITLE     |             |
|      |            |             |        |      |        |       |          | PROJECTION  |  | UNIT | SCALE                  | TOLERANCE        |           | NAME        |
|      |            |             |        |      |        |       |          |  |  | mm   | 33/100                 | KS B ISO 2768-mk |           |             |
|      |            |             |        |      |        |       |          | SECTION   |  |      | ROBOT DEVELOPMENT TEAM |                  |           | DRAWING NO. |
| SYM. | NO OF REV. | DESCRIPTION | EC NO. | DATE | DESIGN | APPR. | APPROVED |   |  |      | CADCHK                 |                  | ZRA_0501N | SHEET NO.   |
|      |            |             |        |      |        |       | DESIGNED |   |  |      | CHECKED                |                  |           |             |
|      |            |             |        |      |        |       |          |   |  |      |                        |                  |           | 1-1         |